

### Annexure A

S. No.	Name of equipment	Qty	Remarks
01.	Monitor Control and PFC Developers Kit <ul style="list-style-type: none"> <li>• Piccolo F28035 control card</li> <li>• PFC and dual motor control baseboard with onboard</li> <li>• Isolated USBJTAG emulation</li> <li>• 24V DC desktop power supply</li> <li>• 55W permanent magnet motor</li> <li>• Code composer V3.3 with 32KB code size limit</li> <li>• Detailed example software and documentation</li> </ul>	01 no.	
02.	Stellaris® AC Induction Motor Reference Design Kit <ul style="list-style-type: none"> <li>• Main control circuit board with a factory installed heatsink</li> <li>• 3 – phase selni appliance AC motor (0-20000 rpm)</li> <li>• Power cables</li> <li>• USB cable</li> <li>• Graphical control program for windows™ on CD</li> </ul>	01 no.	
03.	Integrated Motor Driver for Brushed and Stepper Motors with Piccolo F28035 control card <ul style="list-style-type: none"> <li>• DRV8412 power module base board with control Card interface (2 x H-Bridge)</li> <li>• C2000 Piccolo F28035 control Card (Pre-flashed with code to spin all motors using GUI)</li> <li>• GUI- isolated XDS100 Emulation and serial connectivity</li> <li>• 2 Brushed Motors (38mm)</li> <li>• 1 Stepper Motor (23Y Square)</li> <li>• 24V power supply – USB cable- wiring for motors</li> </ul>	01 no.	
04.	3-Phase BLDC Motor Kit with DRV8312 and Stellaris MCU <ul style="list-style-type: none"> <li>• MDL-LM35818CNCD control Card module</li> <li>• DRV8312 baseboard (TI-integrated 3P motor driver board supporting up to 52.5V and 6.5A)</li> <li>• NEMA17 BLDC/PMSM 55W motor</li> <li>• 24V 2.5A DC power adapter, 110-240V AC input, USA power cable</li> <li>• USB-mini B to USB-A plug cable (for debug and serial communication)</li> </ul>	01 no.	
05.	Function Generator <ul style="list-style-type: none"> <li>• 2 to 20 Mhz</li> <li>• Square, Sine, Triangular waveform</li> </ul>	02 nos.	
06.	Bread board with inbuilt 0-15V DC power supply	04 nos.	
07.	Power supply – DC 0-30V, 2A	02 nos.	
08.	Robotic arm	01 no.	
09.	Trainer for study of microprocessor control of a simulated linear system	01 no.	
10.	Trainer for supply of characteristics of a 2- phase a. c. motor <ul style="list-style-type: none"> <li>• With the determination of forque – speed characteristics, inertia and friction parameters of an a. c. motor</li> <li>• With transfer function evaluation</li> </ul>	01 no.	

